

MLFB-Ordering data

6SL3210-1KE23-8UF1



Client order no. : Item no.: Order no. : Consignment no. : Offer no. : Project : Remarks:

Rated data			General tech. specifications		
Input			Power factor λ	0.70 0.85	
Number of phases	3 AC		Offset factor cos φ	0.95	
Line voltage	380 480 V +10 % -20 %		Efficiency η	0.97	
Line frequency	47 63 Hz		Sound pressure level (1m)	66 dB	
Rated current (LO)	48.20 A		Power loss	0.50 kW	
Rated current (HO)	45.20 A		Filter class (integrated)	Unfiltered	
Output			Ambia	nt conditions	
Number of phases	3 AC		Affiblei	nt conditions	
Rated voltage	400V IEC	480V NEC	Cooling	Air cooling using an integrated fan	
Rated power (LO)	18.50 kW	25.00 hp			
Rated power (HO)	15.00 kW	20.00 hp	Cooling air requirement	0.018 m³/s (0.636 ft³/s)	
Rated current (LO)	37.00 A		Installation altitude	1000 m (3280.84 ft)	
Rated current (HO)	31.00 A		Ambient temperature		
Rated current (IN)	38.00 A		Operation	-10 40 °C (14 104 °F)	
Max. output current	62.00 A		Transport	-40 70 °C (-40 158 °F)	
Pulse frequency	4 kHz		Storage	-40 70 °C (-40 158 °F)	
raise frequency	1 1112		Relative humidity		
Output frequency for vector control	0 240 Hz		Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible	
Output frequency for V/f control	0 550 Hz				
			Closed-loop control techniques		

Overload capability

Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

Closed-loop control techniques				
V/f linear / square-law / parameterizable	Yes			
V/f with flux current control (FCC)	Yes			
V/f ECO linear / square-law	Yes			
Sensorless vector control	Yes			
Vector control, with sensor	No			
Encoderless torque control	No			
Torque control, with encoder	No			



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03	L3210-1KE23-8UF1		Figure	
Mechanical data		Com	Communication	
Degree of protection	IP20 / UL open type	Communication	PROFINET, EtherNet/IP	
iize	FSC	Connections		
Net weight	4.40 kg (9.70 lb)	Signal cable		
Width	140 mm (5.51 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 1	
Height	295 mm (11.61 in)	Line side		
Depth	208 mm (8.19 in)	Version	Plug-in screw terminals	
Inputs / outputs		Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG	
andard digital inputs		Motor end		
Number	6	Version	Plug-in screw terminals	
Switching level: 0→1	11 V	Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG	
Switching level: 1→0	5 V	DC link (for braking resistor)	
Max. inrush current	15 mA	Version	Plug-in screw terminals	
nil-safe digital inputs		Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG	
Number	1	Line length, max.	15 m (49.21 ft)	
gital outputs		PE connection	On housing with M4 screw	
Number as relay changeover contact	1	Max. motor cable length		
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)	
Number as transistor	1	Unshielded	150 m (492.13 ft)	
Output (resistive load)	DC 30 V, 0.5 A	S	Standards	
nalog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
Number	1 (Differential input)			
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Vol Directive 2006/95/EC	
vitching threshold as digital in	out			
0→1	4 V			
1→0	1.6 V			
nalog outputs				

PTC/ KTY interface

Number

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$

1 (Non-isolated output)



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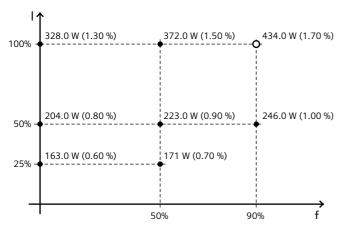
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Figure similar

Converter losses to IEC61800-9-2*

Efficiency class	IE2
Comparison with the reference converter (90% /	34.10 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values